

Contact: Michele Sewart, PMP | Scoliosis Research Society  
[msewart@srs.org](mailto:msewart@srs.org) |414-231-8158

**Scoliosis Research Society Announces**

**2025 Biedermann Innovation Award Winner**

During the 60th Annual Meeting in Charlotte, North Carolina, the Scoliosis Research Society (SRS) will announced this year’s recipient of the Lutz Biedermann award recognizing innovation in the field of spinal deformity.

[The Biedermann Innovation Award](https://www.srs.org/professionals/research-and-journal/research-grants) is designed to support innovative research by a young clinical investigator in the field of spinal deformity. The award is available to SRS members age 45 or younger at the time of the award. Award winners will have demonstrated clinical or translational research promise and submit a research proposal designed to enhance innovation in spinal deformity treatment. All applications are reviewed and selected by the SRS Research Grant Committee.

SRS is pleased to announce this year’s Biedermann Innovation Award Winner: Improving Materials for Vertebral Body Tethering Using Soft Tissue Allografts by R. Carter Clement for $72,699 over two years.

For more information on SRS Grant opportunities, [visit our website](https://www.srs.org/professionals/research-and-journal/research-grants). To contribute to grant research funding, [review all the ways you can donate to SRS.](https://www.srs.org/professionals/research-and-journal/donate)

**About Scoliosis Research Society**

The Scoliosis Research Society is a non-profit, professional organization, made up of physicians and allied health personnel. Our primary focus is on providing continuing medical education for health care professionals and on funding/supporting research in spinal deformities. Founded in 1966, SRS has gained recognition as the world's premier spine deformity society. Please visit [www.srs.org](http://www.srs.org/) for further information. Also follow us on [X](https://twitter.com/SRS_org), [Facebook](https://www.facebook.com/ScoliosisResearchSociety), [LinkedIn](https://www.linkedin.com/company/srs_org) and [Instagram](https://www.instagram.com/srs_org/).

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